



P.E.S. College of Engineering, Mandya - 571 401

(An Autonomous Institution affiliated to VTU, Belgaum)

**Third Semester, B.E. - Electronics and Communication Engineering
Semester End Examination; Dec. – 2015**

Fundamentals of Signals

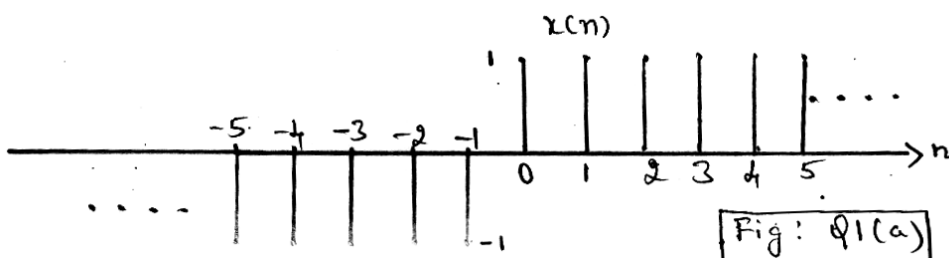
Time: 3 hrs

Max. Marks: 100

Note: i) Answer **FIVE** full questions, selecting **ONE** full question from each unit.
ii) Justify the assumptions made if any

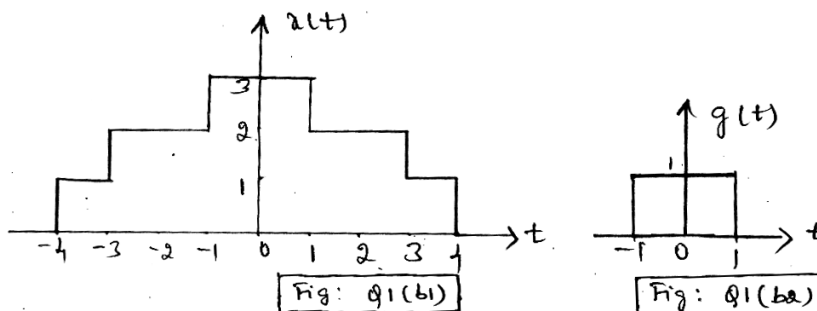
UNIT - I

1 a. Give the definition for even and odd signal. Determine and sketch the even and odd components of the discrete time signal $x(n]$ shown in Fig. 1(a)



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b. Two continuous time signal $x(t)$ and $g(t)$ are shown in Fig. Q1(b1) and Q1(b2) respectively Construct and expression $x(t)$ in terms of $g(t)$.



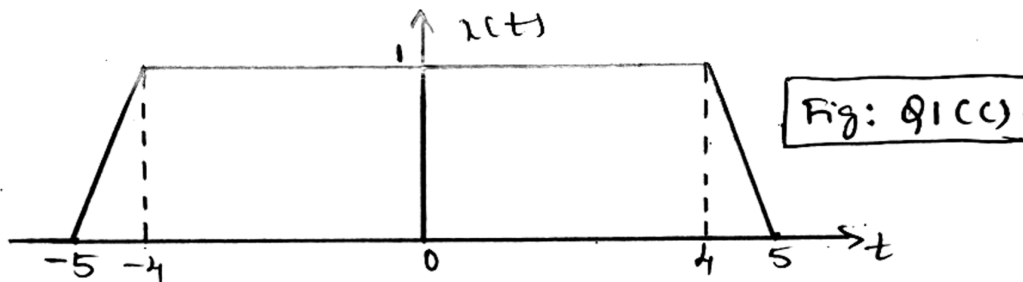
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c. Define energy and Power signal. The trapezoidal pulse $x(t)$ shown in Fig. Q 1(c) is applied to a differentiator defined by

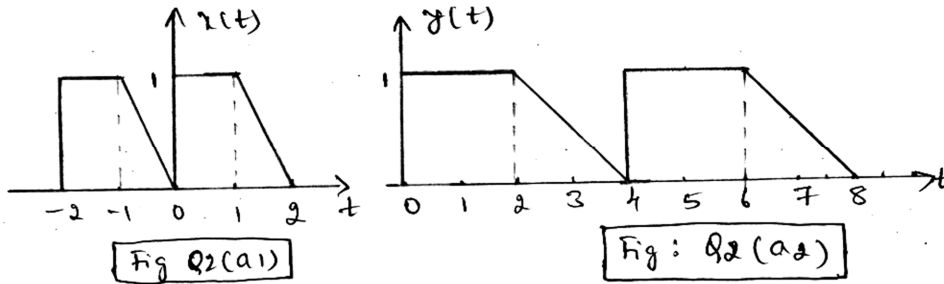
$$y(t) = \frac{d}{dt} x(t)$$

- i) Find the resulting output $y(t)$ of the differentiator
- ii) Find the total energy of $y(t)$

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2 a. Upon applying the time scaling and time shifting operator on the signal $x(t/2)$ shown in Fig. Q2 (a1) we obtain the signal $y(t)$ as depicted in Fig. Q.2 (a2). Determine the signal $y(t)$



b. Determine whether the following systems are i) Linear ii) Time Invariant iii) Casual iv) Memory less v) Stable

A) $y(n) = x(n) + u(n+1)$ B) $y(t) = x(t/2)$

c. Determine whether the following signals are periodic or not. If periodic find its fundamental period.

i) $y(t) = (\cos 2\pi t)u(t)$ ii) $x(n) = x(-1)^n$

UNIT - II

3 a. Consider the input signal $x(n)$ and the impulse response $h(n)$ given by

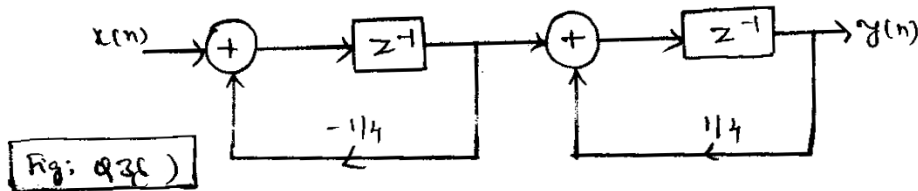
$$\begin{aligned} x(n) &= 1 && ; && 0 \leq n \leq 4 \\ &= 0 && ; && \text{otherwise} \\ h(n) &= \alpha^n && ; && 0 \leq n \leq 6 && ; && \alpha > 1 \\ &= 0 && ; && \text{otherwise} \end{aligned}$$

Compute the output signal $y(n)$

b. Find the step response for the LTI system represented by the impulse response.

$h(n) = (\frac{1}{2})^n u(n)$. Also investigate whether the system is stable and causal.

c. Find the input output relation corresponding to the system shown in Fig. Q3(c).



4 a. Consider a LTI system with unit impulse response $h(t) = u(-t+2)$

If the input applied to this system is

$x(t) = [(u(t+2) - u(t-1))]$

Find the output $y(t)$ of the system.

b. Find the output of the LTI system given by the differential equation

$$\frac{d^2 y(t)}{dt^2} + \frac{5dy(t)}{dt} + 4y(t) = \frac{dx(t)}{dt}$$

with $y(0) = 0$; $\left. \frac{dy(t)}{dt} \right|_{t=0} = 1$ and $x(t) = e^{-2t}u(t)$

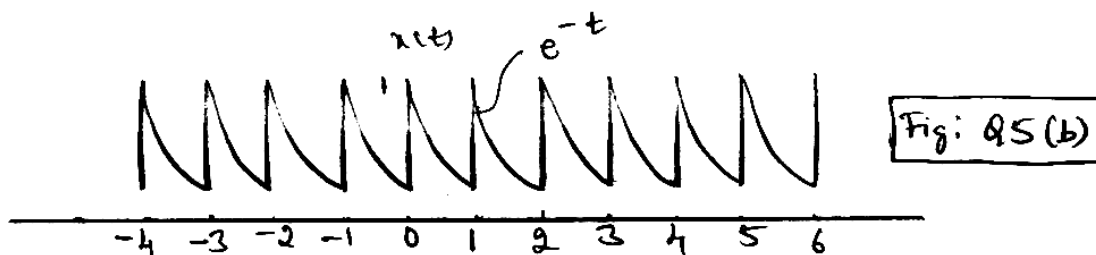
- c. Sketch the direct form I and direct form II implementations for the LTI system whose difference equation is

$$y(n] - \frac{1}{4}y[n-1] + \frac{1}{8}y[n-2] = x[n] + \frac{1}{2}x[n-2]$$

UNIT - III

- 5 a. State and prove the following properties of Fourier series i) Time shift ii) Parseval's theorem

- b. For the signal x(t) shown in Fig. Q 5(b), find the Fourier series representation and draw its magnitude and phase spectra

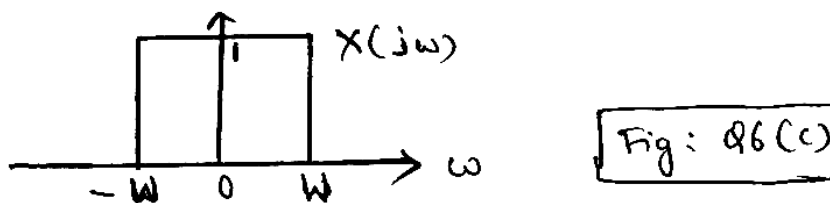


- 6 a. State and prove the following properties of Fourier Transform.

- i) Frequency shift ii) Convolution.

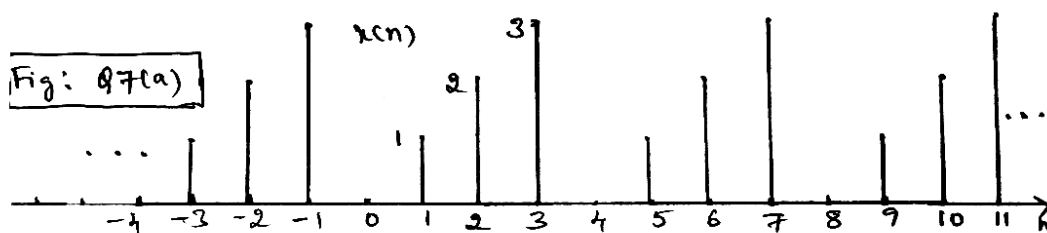
- b. Determine the Fourier Transform of the unit impulse function and draw its spectrum.

- c. Find the time domain signal corresponding to the spectrum shown in Fig. Q6(c)



UNIT - IV

- 7 a. Evaluate the discrete Time Fourier series representation for the signal x(n) shown in figure Q7(a) and sketch the spectra. Also verify Parseval's identify.

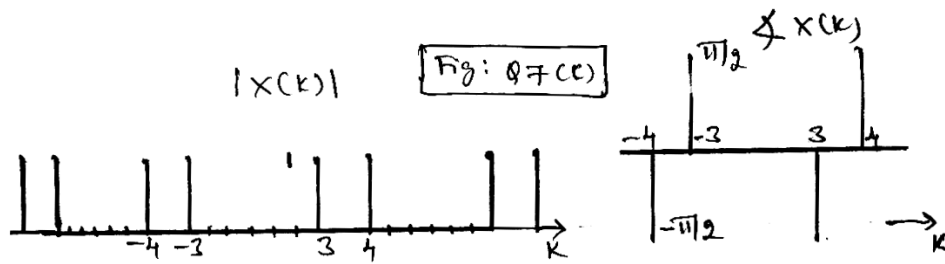


- b. Determine the DTFS coefficients of the periodic sequence given by

$$x(n) = \sum_{m=-\infty}^{\infty} \delta(n-4m)$$

Draw the spectrum.

- c. Determine the time domain signal corresponding to the following spectra shown in Fig. Q7(c).



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- 8 a. Show that the DTFT of the unit step sequence is given by $x(e^{j\Omega}) = \frac{1}{1 - e^{-j\Omega}} + \pi \sum_{k=-\infty}^{\infty} \delta(\Omega - 2\pi k)$ 6
- b. Find the inverse DTFT of the following: i) $x(e^{j\Omega}) = 1 + 2 \cos \Omega + 3 \cos 2\Omega$ 6
 ii) $x(e^{j\Omega}) = j(3 + 4 \cos \Omega + 2 \cos 2\Omega) \sin \Omega$
- c. Define sampling Theorem. Consider the analog signal $x_a(t) = 3 \cos 50\pi t + 10 \sin 300\pi t - \cos 100\pi t$
- i) What is the Nyquist rate for this signal
- ii) What are the frequencies in radians, in the resulting discrete time signal $x(n)$, if the signal is sampled at Nyquist rate. 8
- iii) Suppose that we sample the signal at a rate of 200 samples/second, what is the highest frequency that can be represented uniquely at this sampling rate.

UNIT - V

- 9 a. State and prove the following properties of Z-transform. 7
 i) Time reversal ii) convolution
- b. Determine the Z-transform of the signal $x(n) = -u(-n-1) + (\frac{1}{2})^n u(n)$ 7
 Find the ROC and pole zero locations of $x(z)$ in the Z-plane.
- c. $X(Z) = \frac{\frac{1}{4}Z^{-1}}{(1 - \frac{1}{2}z^{-1})(1 - \frac{1}{4}z^{-1})}$ with ROC: $\frac{1}{4} < |z| < \frac{1}{2}$ 6
- 10 a. We want to design a casual discrete time LTI system with the property that if the input is $x(n) = (\frac{1}{2})^n u(n) - \frac{1}{4}(\frac{1}{2})^{n-1} u(n-1)$ then the output is $y(n) = (\frac{1}{3})^n u(n)$. Determine the system function $H(z)$ and the impulse response of the system that satisfies this condition. 6
- b. A LTI discrete time system is given by the system function $H(z) = \frac{3 - 4z^{-1}}{1 - 3.5z^{-1} + 1.5z^{-2}}$ 6
 Specify the ROC of $H(z)$ and determine $h(n)$ for the following conditions:
 i) The system is stable ii) The system is causal
- c. Solve the following difference equation using unilateral Z-transform 8
 $y(n) - \frac{3}{2}y(n-1) + \frac{1}{2}y(n-2) = x(n)$ for $n \geq 0$
 With $y(-1) = 4, y(-2) = 10$ and $x(n) = (\frac{1}{4})^n u(n)$

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