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P.E.S. College of Engineering, Mandya - 571 401

(An Autonomous Institution affiliated to VTU, Belgaum)

Fifth Semester, B.E. - Mechanical Engineering

Semester End Examination; Dec. - 2014

Mechatronics and Microprocessor

Time: 3 hrs

Max. Marks: 100

Note: Answer any FIVE full questions, selecting at least TWO full questions from each part.

PART - A

1. a. With a block diagram, explain the basic elements of a closed loop control system. 10
- b. With a basic element of a micro – processor – based controls explain the engine management system. 10
- 2 a. Explain the following terms,
 - i) Light sensors 6
 - ii) Tactile sensors
 - iii) Proximity sensors
- b. With a suitable sketches, explain the following type of sensors,
 - i) Hall effect sensors 14
 - ii) Piezo electric sensors.
- 3 a. With a circuit diagram, explain MOSFETs, diodes and thyristors. 8
- b. With a sketch, explain the following types of stepper motors.
 - i) Variable reluctance stepper motor. 12
 - ii) Permanent magnet stepper motor.
 - iii) Hybrid stepper motors.
- 4 a. Briefly explain the signal conditioning process. 6
- b. With a block diagram and sketch explain analogue to digital conversion (ADC) 8
- c. Explain with a block diagram multiplexers 6

PART-B

- 5 a. With a simple sketch, explain the general form of a micro-processor system. 10
- b. With a suitable examples explain the following:
 - i) Mnemonic codes 10
 - ii) Machine and assembly languages
 - iii) High level language programming
- 6 a. Explain with various elements of 8085a architecture (Intel 8085 processor) 12

- b. Explain the following types of buses,
- i) Data bus
 - ii) Address bus
 - iii) Control bus
 - iv) Instruction types.
- 7 a. With simple sketches, explain the timing and control units for the microprocessor.
- b. Explain memory and Input / output cycles to write and read for a microprocessor based system.
- c. Explain the following terms,
- i) HALT and HOLD STATES
 - ii) Initiating system operations
 - iii) Transition sequence.
8. a. Explain with one example each for the following,
- i) Positional number system
 - ii) Binary number system
 - iii) Decimal number system.
- b. With an example explain the following terms,
- i) Addition and subtraction of binary integers
 - ii) Overflow and underflow of integers
 - iii) Accuracy and range in floating point representation.

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