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## P.E.S. College of Engineering, Mandya - 571 401

(An Autonomous Institution affiliated to VTU, Belgaum)

Second Semester, M. Tech - Mechanical Engineering (MMDN)

Make - up Examination; July - 2016

Advanced Theory of Vibrations

Time: 3 hrs

Max. Marks: 100

**Note:** i) Answer **FIVE** full questions, selecting **ONE** full question from each unit.

ii) Assume suitable missing data if any.

### UNIT - I

1. A single degree of freedom spring-mass-damper system with  $m = 0.1$  kg,  $k = 1000$  N/m and  $C = 10$  N-s/m is subjected to excitation force which varies as shown in Fig. Q(1). Obtain the response equation of the system by considering the first three harmonics of the forcing function. 20
- 2 a. One cycle of the forcing function shown in Fig. Q 2(a) is split into twelve divisions and the magnitudes of force at different instants of time are shown in Table Q 2(a). Obtain the first three harmonic components of the forcing functions. 10
- b. Use convolution integral to determine the response of an undamped single degree of freedom system due to triangular pulse shown in Fig. Q 2(b). 10

### UNIT - II

- 3 a. Discuss about coordinate coupling and existence of different types of coupling in a system. 6
- b. Obtain flexibility and stiffness matrix for the system shown in Fig. Q 3(b) and show that they are inverse to each other. 14
4. For the system shown in Fig. Q (4), obtain the natural frequencies and mode shapes. 20

### UNIT - III

5. Obtain the response equation for the free vibration of a string with both ends fixed. 20
6. Find the natural frequencies and free vibration (longitudinal) solution of a bar fixed at one end and free at the other. 20

### UNIT - IV

- 7 a. Derive the expression for ratio of absolute amplitudes of a single degree of freedom spring-mass-damper system subjected to base excitation. 10
- b. With necessary sketches and equation explain the working principle of an accelerometer. 10
- 8 a. With necessary sketches explain frequency measuring instruments. 8
- b. Sketch and explain two types of mechanical vibration exciters. 12

Contd...2

UNIT - V

- 9 a. Write any four differences between linear and non-linear vibrating systems. 4
  - b. With necessary sketches and equations discuss about two non-linear systems. 8
  - c. Discuss method of isoclines for constructing trajectory of a linear system. 8
  - 10 a. Discuss about phase plane trajectories for a linear system. 8
  - b. A system with dry friction damping has its differential equation of motion given by  $\ddot{x} + \phi(\dot{x}) + x = 0$ , where  $\phi(x) = F$  where  $\dot{x}$  is positive and  $\phi(\dot{x}) = -F$  where  $\dot{x}$  is negative. 12
- Obtain trajectory of motion when the system is given an initial displacement and released.

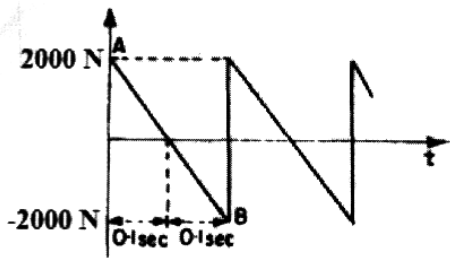


Fig.Q (1)

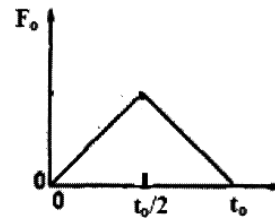


Fig.Q 2(b)

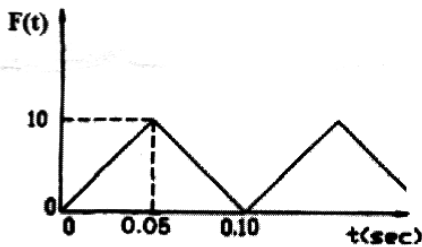


Fig.Q 2(a)

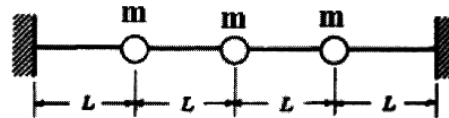


Fig.Q 3(b)

i	F(t) <sub>i</sub>
1	1.67
2	3.33
3	5.00
4	6.67
5	8.33
6	10.00
7	8.33
8	6.67
9	5.00
10	3.33
11	1.67
12	0.00

Table Q 2(a)

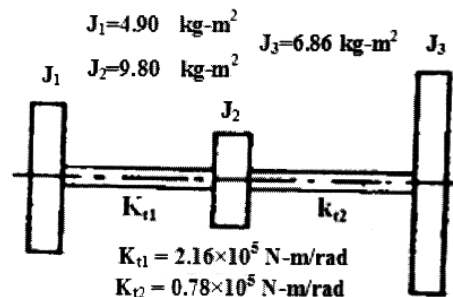


Fig.Q (4)