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P.E.S. College of Engineering, Mandya - 571 401 (An Autonomous Institution affiliated to VTU, Belagavi) Third Semester, M. Tech - Mechanical Engineering (MCIM) Semester End Examination; Dec - 2017 / Jan - 2018 Industrial Sensors and Analysis Technique Time: 3 hrs		
Not	e: Answer FIVE full questions, selecting ONE full question from each unit.	
	UNIT - I	
1 a.	With a neat sketch, explain the principle of operation of inductive proximity sensor.	10
b.	Discuss the characteristics and working principle of microwave sensor.	10
2 a.	With a neat sketch, explain the detection modes used by photoelectric sensors.	10
b.	With a relevant sketch, explain the open loop and closed loop control system.	10
	UNIT - II	
3 a.	Discuss the software problems in evaluation of an existing flexible manufacturing cell using a sensing network.	10
b.	Briefly explain the functional parameters in manufacturing system, sensors and control systems that are used to design manufacturing facilities.	10
4 a.	With a neat block diagram, explain how message movement takes place with a computer network?	10
b.	With an example, explain the working of RS232 based networks.	10
	UNIT - III	
5 a.	Sketch and explain the working of ultrasonic stress sensor measuring dynamic changes in materials.	10
b.	With the help of a block diagram, explain the data flow in an automatic bearing fault detection system.	10
6 a.	With a neat sketch, explain the working of optoelectronic sensor in tracking targets on a structure.	10
b.	With a neat sketch how sensors are used in measuring vibrations in a structure? Explain. UNIT - IV	10
7 a.	Briefly explain semiconductor temperature detector using photoluminescence.	10
b.	Explain the control of input/output speed of continuous web fabrications using laser doppler velocity sensor.	10
8a.	Explain the use of flow sensors in detecting small air bubbles for process control in manufacturing.	10
b.	Briefly explain how the piezoelectric crystals and strain gauges are used as pressure sensor.	10

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UNIT - V

- 9 a. Explain the working of end effectors camera sensor detecting partially visible objects.
 - b. Briefly explain the conditions that govern the performance of sound vision recognition 10 sensors in robot end effectors.
- 10 a. Explain the working of linear variable displacement transformer sensor in robot end effectors.
 - b. Explain the basic parameters of end effectors camera sensor used for edge detection and 10 extraction.

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