



**P.E.S. College of Engineering, Mandya - 571 401**

*(An Autonomous Institution affiliated to VTU, Belagavi)*

**Third Semester, B.E. - Electronics and Communication Engineering**

**Semester End Examination; Dec. - 2019**

**Signals and Systems**

Time: 3 hrs

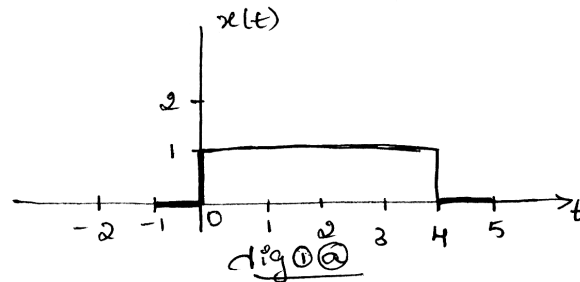
Max. Marks: 100

*Note: Answer FIVE full questions, selecting ONE full question from each unit.*

**UNIT - I**

1 a. A continuous signal  $x(t)$  is shown in Fig. 1(a). Sketch and label each of the following:

- (i)  $x(t-2)$
- (ii)  $x(2t)$
- (iii)  $x(t/2)$
- (iv)  $x(-t)$



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b. Identify whether the following signals are energy or power signals? Also find its corresponding value.

i)  $x_1(n) = \cos(\pi n) \quad ; -4 \leq n \leq 4$   
 $= 0 \quad ; \text{otherwise}$

ii)  $x_2(n) = \cos(\pi n) \quad ; n \geq 0$   
 $= 0 \quad ; \text{otherwise}$

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c. Find the even and odd components of the signal  $x(t) = \cos(t) + \sin(t) + \sin(t)\cos(t)$

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2 a. Determine whether the given signals are periodic. Determine the fundamental period, if periodic,

i)  $x(t) = e^{i(\pi t - 1)}$

ii)  $x(t) = \cos 2t + \sin 3t$

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iii)  $x(n) = \cos\left(\frac{\pi n^2}{8}\right)$

iv)  $x(n) = \sum_{K=-\infty}^{\infty} \{ \delta(n-3k) + \delta(n-k^2) \}$

b. For the following system, illustrate whether the system is linear, time invariant, memory, stable and causal.

i)  $y(n) = x(n - n_d)$

ii)  $y(n) = \log_{10}(|x(n)|)$

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iii)  $y(t) = x\left(\frac{t}{2}\right)$

iv)  $y(n) = x(n) \sum_{K=-\infty}^{\infty} \delta(n-2k)$

c. Define unit impulse in continuous time and discrete time and explain its importance.

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**UNIT - II**

3 a. Prove the following identities,

i)  $x(t) * \delta(t) = x(t)$

ii)  $x(t) * \delta(t - t_0) = x(t - t_0)$

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iii)  $x(t) * u(t) = \int_{-\infty}^t x(\tau) d\tau$

iv)  $x(t) * u(t - t_0) = \int_{-\infty}^{t-t_0} x(\tau) d\tau$

b. An LTI system is characterized by  $h(n) = \left(\frac{3}{4}\right)^n u(n)$ . Compute the output of the system at time,  $n = 5, -5, 10$ , when input  $x[n] = u[n]$ .

10

4 a. Determine the output of the system given by the differential equation with initial condition as

$$\frac{d^2y(t)}{dt} + \frac{5dy(t)}{dt} + 4y(t) = \frac{dx(t)}{dt} \quad 10$$

$$y(0) = 0; \left. \frac{dy(t)}{dt} \right|_{t=0} = 1 \text{ and } x(t) = e^{-2t}u(t)$$

b. Implement the equations given below in direct form I and II structure,

$$\text{i) } y(n) - \frac{1}{4}y(n-1) + \frac{1}{8}y(n-2) = x(n) + \frac{1}{2}x(n-2) \quad \text{ii) } \frac{d^2y(t)}{dt^2} + \frac{5dy(t)}{dt} + 4y(t) = \frac{dx(t)}{dt} \quad 10$$

**UNIT - III**

5 a. Evaluate the DTFS representation for the signal  $x(n) = \sin \frac{4\pi}{21}n + \cos \frac{10\pi}{21}n + 1$ . Sketch magnitude and phase spectra. 10

b. State and prove Convolution Property using Fourier series definition. 10

6 a. Determine the FS representation for the signal  $x(t) = \cos 4t + \sin 8t$ . 5

b. Consider the signal  $x(n) = 2 + 2 \cos \frac{\pi}{4}n + \cos \frac{\pi}{2}n + \frac{1}{2} \cos \frac{3\pi}{4}n$  10

i) Determine and sketch its power density spectrum.

ii) Evaluate the power of the signal.

c. State and prove Linearity Property using FS definition. 5

**UNIT - IV**

7 a. State Sampling theorem. Explain Over Sampling and Under Sampling. 10

b. Using frequency differentiation property find inverse Fourier transform of,

$$X(j\omega) = \frac{j\omega}{(2 + j\omega)^2} \quad 6$$

c. Find the Nyquist rate for the signal, i)  $x_1(t) = \sin c(200t)$  ii)  $x_2(t) = \sin c^2(200t)$  4

8 a. Find D.T.F.T for the given signal, i)  $x(n) = \alpha^n u(n); |\alpha| < 1$  ii)  $x(n) = (-1)^n u(n)$  10

b. State and prove Parseval's theorem using DTFT definition. 10

**UNIT - V**

9 a. Find the Z-transform of,

i)  $x(n) = -\alpha^n u(-n-1)$ . Specify its ROC. 10

ii)  $x(n) = -u(-n-1) + \left(\frac{1}{2}\right)^n u(n)$ . Determine ROC and analyze pole zero plot.

b. Find the inverse Z-transform using partial fraction expansion method,

$$x(Z) = \frac{Z^3 + Z^2 + \frac{3}{2}Z + \frac{1}{2}}{Z^3 + \frac{3}{2}Z^2 + \frac{1}{2}Z} \text{ ROC: } |Z| < \frac{1}{2} \quad 10$$

10 a. A causal LTI system is described by the difference equation,

$$y(n) = y(n-1) + y(n-2) + x(n-1) \quad 10$$

i) Determine the system function H(z) and plot the corresponding ROC.

ii) Determine the impulse response of the system.

b. Solve the difference equation  $y(n) + 3y(n-1) = x(n)$  with  $x(n) = u(n)$  and the initial condition  $y(-1) = 1$  using Z-transform method. 10