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**P.E.S. College of Engineering, Mandya - 571 401**  
 (An Autonomous Institution affiliated to VTU, Belagavi)  
**Seventh Semester, B.E. - Electrical and Electronics Engineering**  
**Semester End Examination; Jan. / Feb. - 2021**  
**AC and DC Drives**

Time: 3 hrs

Max. Marks: 100

**Note:** Answer **FIVE** full questions, selecting **ONE** full question from each unit.

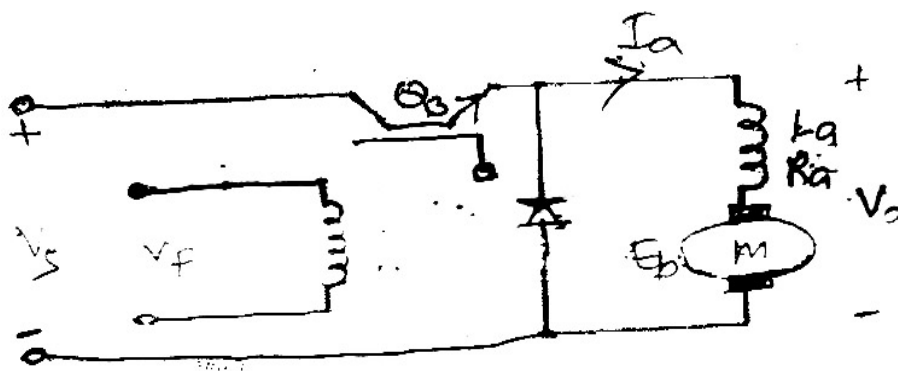
**UNIT - I**

- 1 a. With the help of neat diagram and necessary equations, explain the speed torque characteristics of separately excited DC motor. 6
- b. With relevant circuit and waveforms, explain the operation of single phase half controlled converter fed separately excited DC motor drive under continuous and discontinuous mode. 14
- 2 a. Draw the block diagram of an electric drive. State different classifications of power modulator and explain them in brief. 8
- b. 220 V, 960 rpm, 12.8 A, separately excited DC motor has armature circuit resistance and inductance of 2  $\Omega$  and 150 mH respectively. It is fed from a single phase half controlled rectifier with an AC source voltage of 230 V, 50 Hz. Calculate; 12
- i) Motor torque for  $\alpha = 60^\circ$  and Speed = 600 rpm
- ii) Motor speed for  $\alpha = 60^\circ$  and Torque = 20 N-m

**UNIT - II**

- 3 a. With the help of circuit diagram and waveform, explain the two quadrant operation of separately excited DC motor when fed from chopper control? 10
- b. The speed of a 20 hp, 300 V, 1800 rpm separately excited DC motor is controlled by a three phase full converter drive. The field current is also controlled by three-phase full converter and is set to the maximum possible value. The AC input is a three phase, Y-connected, 208 V, 60 Hz supply. The armature resistance is  $R_a = 0.25 \Omega$ , the field resistance is  $R_f = 245 \Omega$ , and the motor voltage constant is  $K_v = 1.2 \text{ V/A rad/s}$ . The armature and field current can be assumed to be continuous and ripple free. The viscous friction is negligible. Determine; 10
- i) The delay angle of the armature converter if the motor supplies the rated power at the rated speed
- ii) The no-load speed, if the delay angles are same as in (i) and the armature current at no load is 10% of the rated value
- iii) The speed regulation
- 4 a. Comparison between circulating current mode and non-circulating current mode dual converters. 6

- b. With the help of circuit diagram and waveforms, the motoring and braking operation of a three phase fully controlled rectifier fed separately excited DC motor. 8
- c. A DC separately excited motor is powered by a DC-DC converter as shown in Fig. 4(c) from a 600 V DC source. The armature resistance is  $R_a = 0.05 \Omega$ . The back emf constant of the motor is  $K_v = 1.527 \text{ V/A rad/s}$ . The average armature current is  $I_a = 250 \text{ A}$ . The field current is  $I_f = 2.5 \text{ A}$ . The armature current is continuous and has negligible ripple. If the duty cycle of the DC-DC converter is 60%. Determine;
  - i) The input power from the source
  - ii) The equivalent input resistance of the DC-DC converter drive
  - iii) The motor speed
  - iv) The developed torque6



UNIT - III

- 5 a. Deduce the open loop transfer function of excited DC motor drive and represent the same in block diagram approach. 9
- b. With a neat block diagram of a closed- loop converter-fed DC motor drive, explain the operation of closed loop converter-fed DC motor. 5
- c. With a neat schematic diagram, explain the computer controlled four quadrant DC drive operation. 6
- 6 a. Explain the dynamic braking, counter current braking and regenerative braking of DC shunt motor. 10
- b. Explain the operation of closed loop speed control of DC motor with inner current loop and field weakening. 10

UNIT - IV

- 7 a. Explain the speed torque characteristics of induction motor. Mention the modes of operation. 6
- b. Explain the control regions of the induction motor and infer on the effects of variable parameters on its performance. 7
- c. Explain the principle of variable voltage and variable frequency control of induction motor. 7

- 8 a. With the help of a neat circuit diagram, explain the VSI fed V/F control induction motor drive. 7
- b. Explain the operation of static Scherbius drive. 8
- c. Differentiate between VSI and CSI. 5

**UNIT - V**

- 9 a. Explain the operation of self-controlled synchronous machine. 7
- b. With a neat block diagram, explain the process of cold rolling mill. 7
- c. Explain the applications of industrial drive in textile industry. 6
- 10 a. What is load commutated inverter drive? Explain the principle and controlling operation of synchronous drive using load commutated inverter. 7
- b. With the help of schematic diagram, explain the process and operation of paper mill. 6
- c. With help of schematic diagram, explain the process and operation of cement mill. 7

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