



P.E.S. College of Engineering, Mandya - 571 401
 (An Autonomous Institution affiliated to VTU, Belagavi)
Fifth Semester, B.E. - Electrical and Electronics Engineering
Semester End Examination; Feb. - 2021
Linear Control Systems

Time: 3 hrs

Max. Marks: 100

Course Outcomes

The Students will be able to:

CO1: Do the linear modeling (Transfer Function) for Electrical, Mechanical & Electromechanical systems with the analogy.

CO2: Do the analysis of the second order system with the transient & steady state performance specification & its importance.

CO3: Do the stability analysis of different systems with RH criterion & Root locus technique.

CO4: Do the frequency response analysis using analytical & Bode diagram.

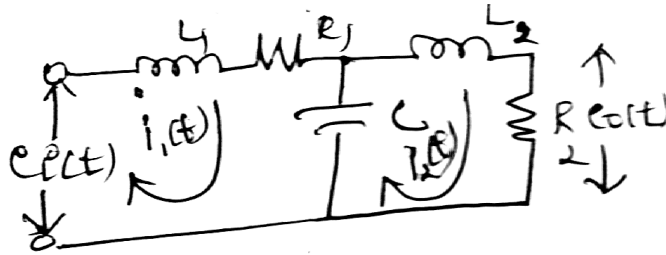
CO5: Do the relative stability analysis using Polar & Nyquist diagrams.

Note: I) PART - A is compulsory. Two marks for each question.

II) PART - B: Answer any **Two** sub questions (from a, b, c) for Maximum of **18 marks** from each unit.

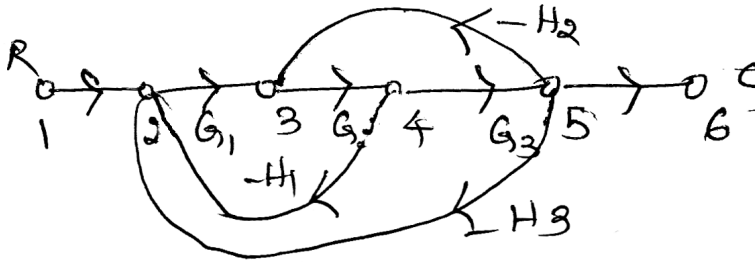
Q. No.	Questions	Marks	BLs	COs	POs
I : PART - A		10			
1 a.	What is a mathematical model? What are the different types?	2	L1	CO1	PO1
b.	Define settling time.	2	L1	CO2	PO1
c.	What are poles and zeros of a system?	2	L1	CO3	PO1
d.	What is a polar plot?	2	L1	CO3	PO1
e.	What is state variable?	2	L1	CO4	PO1
II : PART - B		90			
UNIT - I		18			
1 a. i)	Explain the advantages and disadvantages of block diagram reduction process over signal flow graph.	6	L1	CO1	PO1
ii)	Find the transfer function $E_o(s)/E_i(s)$ of the following network,				
		6	L2	CO1	PO2
b. i)	Obtain the T.F. of the mechanical system shown in figure below,				
		6	L2	CO1	PO2

ii) Find the transfer function $E_o(s)/E_i(s)$ of the network shown below,



6 L1 CO1 PO2

c. Find C/R of the following signal flow graph using Mason's gain formula,



6 L2 CO2 PO2

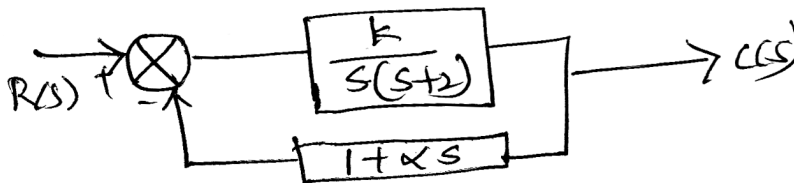
UNIT - II

18

2 a. i) Give the expression for maximum peak overshoot for a second order system.

6 L1 CO2 PO2

ii) Determine the value of K and α such that the system has a damping ratio of 0.7 and an un-damped natural frequency of 4 rad/s for the system shown in figure below,

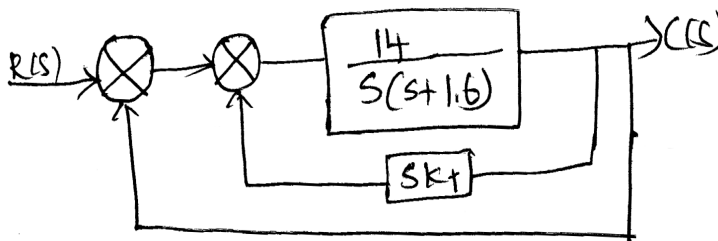


8 L2 CO2 PO3

b. i) Give the expression for rise time of the step response for a second order system.

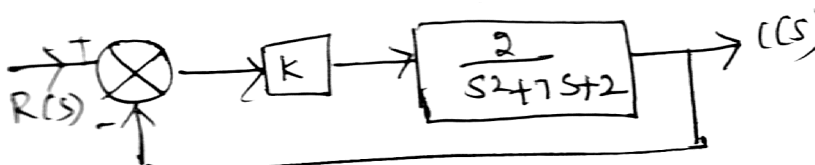
6 L1 CO2 PO2

ii) The system shown in figure below used a rate feedback controller. Determine tachometer constant K_t so as to obtain the damping ratio as 0.5. Calculate corresponding ω_d , t_p , t_s and M_p .



8 L3 CO2 PO3

c. For the control system shown below, what is the value of K for the system to be critically damped?



4 L2 CO2 PO2

UNIT - III

18

- 3 a. i) What are poles and zeros of a system?
 ii) Use Routh's criterion to determine the number of roots of the following equation which lie in the RHS of S plane. $s^6 + s^5 + 2s^4 + s^3 + 2s^2 + 5s + 6 = 0$.
- b. Sketch the root locus of a feedback system whose open loop T.F. is given by,
- c. Sketch the root locus for a unity feedback system with open loop T.F.

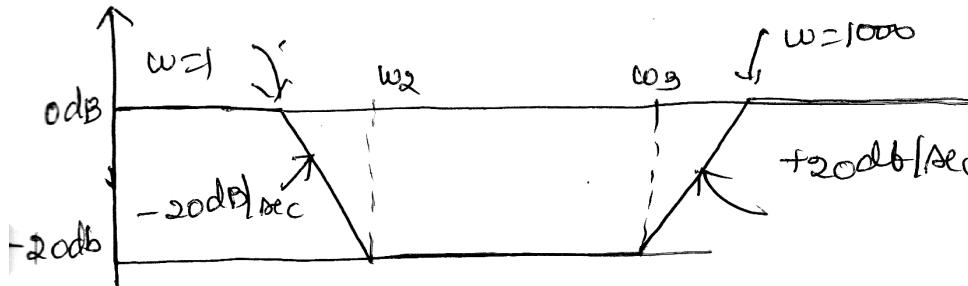
$$G(S)H(S) = \frac{K}{S(S+2)(S+3)}$$

$$G(S) = \frac{K}{S(S^2 + 8S + 32)}$$

UNIT - IV

18

- 4 a. i) List the advantages of frequency response as compared to time domain response.
 ii) Determine the T.F. of a system whose asymptotic gain plot is given below,



- b. i) Define Bandwidth, Resonant peak and Resonant frequency.
 ii) Draw Bode plot and discuss stability
- c. The closed loop T.F. of a feedback system is given by,

$$T(S) = \frac{1000}{(S + 22.5)(S^2 + 2.4S + 44.4)}$$

Determine; i) M_r , ω_r ii) Bandwidth of the equivalent second order system.

UNIT - V

18

- 5 a. Explain the concept of Nyquist stability criterion with example.
 b. Define phase margin and gain margin from polar plot. Consider a system with open loop transfer function as $G(S)H(S) = \frac{10}{S}$. Obtain its polar plot.
 c. For a certain control system $G(S)H(S) = \frac{K}{S(S+2)(S+10)}$ sketch the Nyquist plot and hence calculate the range of values of K for stability.