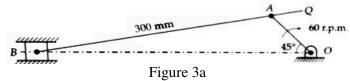
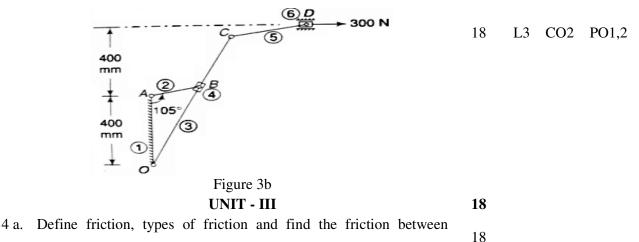
	U.S.N								
P.E.S. College of Engineering, Mandya - 571 401 (An Autonomous Institution affiliated to VTU, Belagavi) Fourth Semester, B.E Automobile Engineering Semester End Examination; Sep. / Oct 2023 Theory of Machines									
Time:	3 hrs		Ма	ıx. Mar	rks: 100				
<ul> <li>Course Outcomes</li> <li>The Students will be able to:</li> <li>CO1: Calculate mobility (number of degrees-of-freedom) and enumerate rigid links and types of joints within mechanisms, and to Understand gear mechanism classification and to become familiar with gear standardization and specification in design.</li> <li>CO2: Explain Terminology of gears and Importance of gear trains and their practical applications.</li> <li>CO3: Know uses and advantages of belt drives Types and their nomenclature, Relationship between belt tensions commonly used design parameters.</li> <li>CO4: Draw inversions and determine velocity and acceleration of different mechanisms, and to Calculate loss of power due to friction in various machine elements and Importance of Governors.</li> <li>CO5: Explain Gyroscopic Effects and Gyroscope in automobile sector.</li> <li>Note: I) PART - A is compulsory. Two marks for each question.</li> </ul>									
II) PART - B: Answer any Two sub questions (from a, b, c) for a Maximum of 18 marks from each unit.Q. No.QuestionsMarks BLsCOsPOs									
	I : PART - A	10							
1 a.	Define kinematic pair and kinematic chain.	2	L1	CO1	PO1,2				
b.	What are the conditions for a body to be in equilibrium under the action of three forces?	2	L1	CO2	PO1,2				
c.	What are the laws of solid dry friction?	2	L1	CO3	PO1,2				
d.	Why is balancing necessary for rotors of high-speed engines?	2	L1	CO4	PO1,2				
e.	What is meant by applied torque and reaction torque?	2	L1	CO5	PO1,2				
	II : PART - B	90							
	UNIT - I	18							
2 a.	With neat sketch, explain any two inversions of double slider crank mechanism.	9	L2	CO1	PO1,2				
b.	With the neat sketch, explain construction and working of crank and slotted lever mechanism.	9	L2	CO1	PO1,2				
c.	Briefly explain classification of kinematic pair.	9	L2	CO1	PO1,2				
	UNIT - II	18							
3 a.	In the slider crank mechanism shown in Figure 3a, the crank OA rotates with a uniform speed of 60 r.p.m. Determine the relative velocity of crank and connecting rod, linear velocity of the slider and point Q located on the connecting rod extended as shown. $AB = 300 \text{ mm}, OA = 75 \text{ mm}, AQ = 50 \text{ mm}.$	18	L3	CO2	PO1,2				

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b. For the static equilibrium of the quick-return mechanism shown in Figure 3b, determine the input torque  $T_2$  to be applied on the link AB for a force of 300 N on the slider D. The dimensions of the various links are OA = 400 mm, AB = 200 mm, OC = 800 mm, CD = 300 mm.



sliding pair with neat sketch. b. With neat sketch, explain different types of follower and explain 18 any three types of motion with displacement diagram. UNIT - IV 18 5 a. Four masses A, B, C and D carried by a rotating shaft at radii 80 mm, 100 mm, 160 mm and 120 mm respectively are completely balanced. Masses B, C, D are 8 kg, 4 kg and 3 kg respectively. 18 CO4 PO1,2,3,5 L3 Determine the mass A and the relative angular positions of the four masses if the planes are spaced 500 mm apart. 5 b. A rotating shaft carries four unbalanced masses 18 kg, 14 kg, 16 kg, and 12 kg at radii 5 cm, 6 cm, 7 cm, and 6 cm respectively. The  $2^{nd}$ , 3<sup>rd</sup> and 4<sup>th</sup> masses revolve in planes 8 cm, 16 cm and 28 cm respectively measured from the plane of the first mass and are angularly located at 60°, 135° and 270° respectively measured anticlockwise from the first mass looking from mass end of the CO4 PO1,2,3,5 18 L3 shaft. The shaft is dynamically balanced by two masses, both located at 5 cm radii and revolving in planes mid way between those of 1<sup>st</sup> and 2<sup>nd</sup> masses and midway between those of 3<sup>rd</sup> and 4<sup>th</sup> masses. Determine the magnitudes of the masses and their respective angular positions. Contd...3

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	UNIT - V	18		
6 a.	Sketch the Hartnell governor. Describe the function and deduce a	a 9	L2	CO5 PO1,2,3,5
	relation to find the stiffness of the spring.			
b.	Each arm of a porter governor is 200 mm long and is pivoted on the			CO5 PO1,2,3,5
	axis of the governor. The radii of rotation of the balls at the	9 L.		
	minimum and maximum speeds are 120 mm and 160 mm		т 2	
	respectively. The mass of the sleeve is 24 kg and each ball is 4 kg.		LS	
	Find the range of speed of the governor. Also find the range of			
	speed if the friction at sleeve is 18 N.			
c.	Each wheel of a motorcycle is of 600 mm diameter and has a	9 L3		CO5 PO1,2,3,5
	moment of inertia of 1.2 kg.m <sup>2</sup> . The total mass of the motorcycle			
	and the rider is 180 kg and combined center of mass is 580 mm			
	above the ground level when the motorcycle is upright. The		т 2	
	moment of inertia of the rotating parts of the engine is 0. 2 kg.m <sup>2</sup> .		LJ	
	The engine speed is 5 times the speed of the wheels and is in the			
	same sense. Determine the angle of wheel necessary when the			
	motorcycle takes a turn of 35 m radius at a speed of 54 km/h.			

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